



Engineering Program

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Technology of remote industrial sensing and controlling
20413252
Actuators Lab
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Brief Course Description:

This covers experimental study and investigation of various types of actuators and their applications in industry.

Course Objectives:

Upon the completion of this course, the student will be able to:

- 1. Study and assemble circuits related with various types of actuators
- 2. Operate and test various types of actuator circuits
- 3. Distinguish between electrical, pneumatic and hydraulic actuators
- **4.** Simulate actuators using special purpose simulation software

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Detailed Course Description:

Chapter No.	Content title	Unit content	Time Needed
1	Experiment 1: Simulation of electrical actuators	 DC motor circuit design AC motor circuit design Utilizing Relays and solenoids 	2
2	Experiment 2: Simulation of Drive system for electrical actuators	DC motor drivingAC motor driving	2
3	Experiment 3: Pneumatic and Electro- pneumatic actuators	Assembly and operate Pneumatic and Electro- pneumatic actuator circuits	1
4	Experiment 4: Electro-hydraulic actuators	Assembly and operate Electrohydraulic actuators	1
5	Experiment 5: Single phase induction motors split phase type		3
6	Experiment 6 Experiments on DC motors ;shunt, series, compound		3
7	Experiment 7 Experiments on three phase induction motors; wound rotor type and squirrel		2
8	Experiment 8: Stepper motor	Working with DC motorsDesign a simple drive system for stepper motor	2

Evaluation Strategies:

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		Percentage	Date	
1. Exams	Mid Exam	20%	1	/20
	Lab activates and	30%	/	/20
	reports			
	Final Exam	50%	/	/20
Total		100%		

Teaching Methodology:

- Working with datasheet
- Practical experimental work in small groups
- PowerPoint slides
- Term projects

Text Books & References:

Textbooks

- 1. Labartory sheet prepared by instructor
- 2. Pneumatics, Basic level, Peter Croser, Frank Ebel
- 3. Hydraulics Basic Level, Workbook TP 50
- 4. Electro-hydraulics Basic levelD. Merkle K. Rupp D. Scholz

References

- 1. Manuals of each type of machines.
- 3. Electric machinery fundamentals, Stephen J.Chapman, 1996.